APPARATUS FOR DELIVERING THE POWER STATUS DATA OF A

SMART BATTERY

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BACKGROUND OF THE INVENTION

Field of the Invention

[0001]   The invention relates in general to a signal delivering apparatus, and more particularly to an apparatus for delivering the power status data signal indicative of the power status of a smart battery.

Description of the Related Art

[0002]   Portable computers are commonly called notebook computers, which are easy for carriage. Without an outer power source, the portable computer uses its battery as the only power source. Therefore, keeping the portable computer supplied with steady power by the battery is a very important issue to the operation of the portable computer system.

[0003]   Currently, the type of battery device used in the portable computer is smart battery device. It can provide the power status data signal indicative of the power status of the battery to the system central processing unit (system CPU) of the portable computer system through the bus between

the system and the battery. Therefore, the system CPU can carry out the

power management task according to the power status data of the smart

battery device. For example, if a user does not give any command through the

keyboard or other peripheral input/output device for a long period of time, the

5   system CPU can shut down the operation of the monitor, hard disk or other

apparatus to reduce the power consumption. When the power in the battery is

consumed under a certain amount, the system CPU can lower the luminance

of the monitor, or deliver a warning message to inform the user that the

battery needs to be recharged. Further, when the power stored in the battery

10   runs out, the system CPU can suspend current data to the memory, or to the

hard disk and then shut down the whole computer system.

[0004]   In the portable computer, an embedded controller is in

charge of delivering the power status data signal of the smart battery. The

system CPU commands the embedded controller to provide the power status

15   data signal of the smart battery to the system CPU regularly. After receiving

the power status data from the embedded controller, the system CPU will

carry out the power management task according to the power status of the

battery device.

[0005]   However, the embedded controller still has to do other tasks

20   in addition to delivering the power status data signal of the smart battery. For

example, the embedded controller has to deliver signals from keyboard or

other peripheral input device, or control play of the CD drive. Because the

system CPU commands the embedded controller to read the power status

data of the smart battery regularly, the embedded controller has to regularly interrupt the task being executed, in order to deliver the power status data of the smart battery. Thus, it has a negative effect upon the performance and efficiency of the embedded controller in executing other tasks. Besides, it takes time for the embedded controller to deliver the power status data of the smart battery to the system CPU through the bus. When the system CPU commands the embedded controller to read the power status data of the smart battery, the system CPU has to regularly interrupt the task being executed to wait for the power status data that is provided by the embedded controller. Therefore, it also has a negative effect upon the performance and efficiency of the system CPU in executing other tasks.

[0006]   The conventional method to improve the delivery of the power status data of the smart battery is to assign a memory block of the basic input/output system (BIOS) to store the power status data. The embedded controller delivers the power status data to the assigned memory block of the basic input/output system instead of delivering to the system CPU directly. The assigned memory block of the basic input/output system stores the power status data. When needed, the system CPU can get the power status data from the assigned memory of the basic input/output system regularly. Therefore, it can reduce the waiting time of the system CPU. The system CPU does not need to interrupt the task being executed to receive the power status data of the smart battery regularly.

[0007]   When the system CPU reads the power status data signal

of the smart battery according to the prior art, there are some disadvantages

still. First, the embedded controller still has to interrupt the task being

executed so as to deliver the power status data of the smart battery regularly

when it is commanded by the system CPU. This still has a negative effect

5   upon the performance and efficiency of the embedded controller in executing

other tasks. Second, it takes time for the basic input/output system to get the

power status data from the embedded controller and store it to the assigned

memory block. The above-mentioned method does not reduce time on

delivering the power status data from the embedded controller to the basic

10   input/output system. Third, the embedded controller is substantially a central

processing unit (CPU). By designing complicated command sets in the

embedded controller, the embedded controller is capable of performing more

complicated functions than that of the common logic circuit. Therefore, the

embedded controller is much more expensive than the common logic circuit.

15   Therefore, it is unnecessary to use such complicated embedded controller to

deliver the power status data of the smart battery. Instead of the embedded

controller, the power status data can be delivered by properly designed logic

devices.

[0008]   In brief, the conventional method to deliver the state of

20   charge of the smart battery has the following disadvantages. First, it has

negative effects upon the performance and efficiency of the embedded

controller for other tasks. Second, it takes a long time to store the power

status data into the basic input/output system. Third, it is not economical to

use the embedded controller to carry out the delivery of the power status data
of the smart battery.

SUMMARY OF THE INVENTION

[0009]   It is therefore an object of the invention to provide an apparatus for
delivering the power status data signal of a smart battery, which has the
following advantages.   First, the performance and efficiency of the embedded
controller in doing other tasks is enhanced. Second, time for the basic
input/output system to read the power status data is decreased. Third, cost for
implementing the power status data delivery is reduced.

[0010]   The invention achieves the above-identified objects by providing an
apparatus for delivering a power status data signal of a smart battery, which
comprises a control device, a data buffer device and a data storage device.
The control device is used for controlling the smart battery to output the power
status data signal according to a smart battery clock signal, and receives and
outputs the power status data signal of the smart battery serially.   The control
device outputs to the smart battery clock signal a first clock signal and a
second clock signal according to a input clock signal. The data buffer device is
used for receiving the power status data signal serially and outputting the
power status data signal in parallel when receiving the first clock signal. The
data storage device is used for receiving the power status data signal in
parallel and outputting the power status data signal in parallel.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011]   Other objects, features, and advantages of the invention will

become apparent from the following detailed description of the preferred but

non-limiting embodiments.   The following detailed description is made with

5   reference to accompanying drawings.

[0012]   FIG. 1 shows a block diagram of an apparatus for delivering the

power status data signal of the smart battery.

[0013]   FIG. 2 shows a timing chart of the signals illustrated in FIG. 1.

10   DESCRIPTION OF THE PREFERRED EMBODIMENT

[0014]   FIG. 1 shows a block diagram of an apparatus for delivering the

power status data signal of a smart battery. The power status data delivering

apparatus100 is to deliver the power status data of the smart battery, without

the use of the conventional embedded controller. The power status data

15   delivering apparatus 100 is coupled to the smart battery device 102 and the

basic input/output system (BIOS) 110. The power status data delivering

apparatus100 includes a control device 104, a data buffer device106 and a

data storage device 108.   As shown in Fig. 1, the control device 104 is

coupled to the smart battery device 102, the data buffer device 106 is coupled

20   to the control device 104 and the data storage device 108 is coupled to the

control device 104, the data buffer device 106 and the basic input/output

system 110 respectively.

[0015]   The system central processing unit (system CPU) outputs an

address signal (add) to command the power status data delivering

5   apparatus100. When receiving the address signal (add), the power status

data delivering apparatus100 starts to deliver the power status data signal.

[0016]   FIG. 2 shows a timing chart of the signals illustrated in FIG. 1. The

control device104 receives the address signal (add) from an address signal

input node (CA) and a clock signal (t) from a clock signal input node (CK). The

10   control device 104 outputs a smart battery clock signal (smbclk) from the

serial clock signal output node (CS) to the smart battery 102, a first clock

signal (out1) from a first clock signal output node (C1) to the data buffer 106,

and a second clock signal (out2) from a second clock signal output node (C2)

to the data storage device108. The timing chart of the clock signal (t), the

15   smart battery clock signal (smbclk), the first clock signal (out1) and the second

clock signal (out2) are shown in FIG. 2. The control device 104 synchronizes

the operation of the smart battery 102, the data buffer device 106 and the data

storage device 108 by outputting the clock signal to them respectively.

[0017]   After receiving the address signal (add) and the clock signal (t), the

20   control device104 outputs the smart battery clock signal (smbclk) from the

serial clock signal output node (CS) to the smart battery 102 through a first

bus. After receiving the smart battery clock signal (smbclk), the smart

battery102 outputs the power status data signal (smbdata) from the power

status data output node (BO) to the control device104 through the first bus.

The power status data signal (smbdata) includes the data of the power status

of the smart battery 102. The power status data signal (smbdata) is delivered

5   serially to the control device104 according to the smart battery clock signal

(smbclk). The format of the power status data signal is decided by the protocol

of the first bus. For example, if the first bus is a system management bus (SM

bus), the format of the power status data signal (smbdata) includes an

address data (address), a command (CMD) and a power status data (data).

10   [0018]   After receiving the power status data signal (smbdata), the control

device104 outputs the first clock signal (out1) from the first clock signal output

node (C1) and the power status data signal (smbdata) from the power status

data output node (CD) to the data buffer device106. The data buffer

device106 receives the first clock signal (out1) from a first clock signal input

15   node (DT) and the power status data signal (smbdata) from the data signal

input node (DI). The power status data signal (smbdata) is delivered to the

data buffer device106 serially. The data buffer device106 includes a plurality

of data buffers. After receiving the power status data signal (smbdata) serially,

the data buffer device106 stores each bit of the power status data signal

20   (smbdata) in each data buffer. The data buffer device106 can deliver the

power status data signal (smbdata) in parallel. The advantage of parallel

signal delivering is that it takes much less delivery time compared to the serial

signal delivering. For example, the data buffer device106 can deliver the

whole power status data signal (smbdata) to the next stage device in one clock period.

[0019]   The control device104 outputs the second clock signal (out2) from the second clock signal output node (C2) to the data storage device108. After receiving the second clock signal (out2), the data storage device108 paralleled receives the power status data signal (pdata) from the data signal input node (EI). The power status data signal (pdata) is delivered from the data buffer device106 to the data storage device108 in one clock period. The data storage device108 is used for latching the power status data signal in the data storage device108.

[0020]   When the basic input/output system commands the power status data signal delivering apparatus100, the charge stage data signal will be delivered in parallel from the data storage device108 to an assigned memory block of the basic input/output system110 through a second bus. The second bus is, for example, a system management bus (SM bus).

[0021]   The power status data signal delivering apparatus 100 is not only for use in the portable computer, but also in other portable apparatus that uses the smart battery as the power source, such as mobile phone, personal digital assistant (PDA).

[0022]   Therefore, the foregoing preferred embodiment of the invention discloses an apparatus for delivering the power status data signal of the smart

battery, which includes the following advantages. First, delivering of the power status data signal of the smart battery to the basic input/output system can be performed by the power status data signal delivering apparatus instead of the conventional embedded controller. Therefore, the embedded controller does

5   not need to interrupt the task being executed to deliver the power status data of the smart battery regularly. It can improve the performance and efficiency of the embedded controller in executing other tasks. Second, the power status data signal delivering apparatus can deliver the power status data signal to the basic input/output system in parallel. In other words, the basic input/output

10   system can receive the whole power status data signal in one clock period. Therefore, compared to the conventional method, it saves a lot of delivering time. Third, the apparatus in the invention can be formed by simple components. Therefore, the power status data signal delivering apparatus is much cheaper than the prior embedded controller. The power status data

15   signal delivering apparatus can replace the conventional embedded controller to deliver the power status data of the smart battery to the basic input/output system. Therefore, the designed function of the embedded controller can be simplified and the cost of the embedded controller can be decreased.

[0023]   While the invention has been described by way of example and in

20   terms of the preferred embodiment, it is to be understood that the invention is not limited to the disclosed embodiment. To the contrary, it is intended to cover various modifications and similar arrangements and procedures, and the scope of the appended claims therefore should be accorded the broadest

interpretation so as to encompass all such modifications and similar arrangements and procedures.